Package 'spacejamr'

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Title Simulate Spatial Bernoulli Networks

Version 0.2.1

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Description Social network analysis is becoming commonplace in many social science disciplines, but access to useful network data, especially among marginalized populations, still remains a formidable challenge. This package mitigates that problem by providing tools to simulate spatial Bernoulli networks as proposed in Carter T. Butts (2002, ISBN:978-0-493-72676-2), ``Spatial models of large-scale interpersonal networks." Using this package, network analysts can simulate a spatial point process or sequence with a given number of nodes inside a geographical boundary and estimate the probability of a tie formation between all node pairs. When simulating a network, an analyst can choose between five spatial interaction functions. The package also enables quick comparison of summary statistics for simulated networks and provides simple to use plotting methods for its classes that return plots which can be further refined with the 'ggplot2' package.

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URL https://github.com/dscolby/spacejamr

BugReports https://github.com/dscolby/spacejamr/issues

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as.spacejamr	• •	2
compare_networks		3
NetSim		4
plot.NetSim		5
plot.PointSim		7
plot.spacejamr		8
PointSim		9
print.NetSim		10
print.PointSim		10
print.spacejamr		
RI		12
spacejamr		13
summary.NetSim		13
summary.PointSim		14
summary.spacejamr		15

Index

as.spacejamr

Initialize a new spacejamr object

Description

Creates a new spacejamr object that for further analysis

Usage

as.spacejamr(path, guess_crs = TRUE)

Arguments

path	the path to a shapefile as a string.
guess_crs	whether to try to guess the coordinate reference system of the supplied shapefile

Details

The returned spacejamr object will contain a window object containing a geographical boundary and its coordinate reference system. Since any simulated point process will be simulated in two dimensions, the coordinate reference system of the supplied shapefile should be a projected coordinate reference system or 'guess_crs' should be set to TRUE. In that case, the coordinate reference system will be set to the most appropriate coordinate reference system for the shapefile. Note that guessing the coordinate reference system will take longer than if one is already set.

16

compare_networks

Value

a spacejamr object containing two items. window: object of class 'owin' that stores geographical boundaries. crs: integer value referring to the coordinate reference system of the geographical boundaries.

Author(s)

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Examples

```
ri <- as.spacejamr(system.file("shape/ri.shp", package = "spacejamr"))</pre>
```

compare_networks Compare statistics from two simulated networks

Description

Generates summary statistics for two simulated networks of class NetSim.

Usage

```
compare_networks(net1, net2)
```

Arguments

net1	a NetSim object
net2	a NetSim object

Details

This function enables a quick comparison of two simulated networks of class NetSim. This allows the user to see how different a network simulated from a Halton sequence is from network simulated from a Poisson point process with the same number of points in the same geographical window. Similarly, it enables comparison of networks generated from different spatial interaction functions. The density, mean degree, mean closeness, mean betweenness, and the size of the largest connected component are computed for each network. Value

A dataframe with two rows and five columns. The first row displays statistics from the first network and the second row displays statistics from the second network. The values in each column are as follows. Density: the density of the network. Mean Degree: the average degree of all nodes in the network. Mean Closeness: the average closeness centrality of all nodes in each network. Mean Betweenness: the average betweenness centrality for the nodes in a network. Largest Component Size: The number of nodes in the largest connected component of a network.

Author(s)

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Examples

```
# load data
data("RI")
# Simulate point processes
points1 <- PointSim(10, RI)
points2 <- PointSim(20, RI)
# Create two networks
net1 <- NetSim(points1)
net2 <- NetSim(points2)</pre>
```

```
compare_networks(net1, net2)
```

NetSim

Simulate a network from a point process or sequence

Description

Simulates a spatial Bernoulli network from a NetSim object using one of six probability law distributions.

Usage

```
NetSim(point_sim, sif, base_prob, scale, threshold, power)
```

Arguments

point_sim	a PointSim object
sif	the spatial interaction function to use. Use attenuated to use an attenuated power
	law; arctan to use an arctangent probability law; decay to use an exponential decay law; or logistic to use a logistic probability law. Default is a standard
	power law function.

4

plot.NetSim

base_prob	the theoretical probability that two nodes (points) with distance 0 share a tie. Default is 0.9.
scale	a coefficient to multiply the distance by. Default is 1.
threshold	if two node exceed this probability, they will be coded as having a tie. Default is 0.5.
power	the exponent at which tie probability decays. Default is -2.8.

Details

The algorithm proceeds in three steps. First, it calculates the distance between simulated points from a PointSim object. Then it calculates the distance between all pairs of points. Finally, it uses a spatial interaction function to calculate that any two point share a tie. If the threshold is exceeded, a tie is created.

Value

A network object of class 'NetSim' and 'igraph' that can be manipulated using the igraph' package.

Author(s)

Darren Colby Email: dscolby17@gmail.com

References

Butts, Carter T. Spatial models of large-scale interpersonal networks. Dissertation. (2002).

Examples

plot.NetSim

Plot a simulated network from a NetSim object

Description

This can take either a PowerLawNetwork or APLNetwork object as input, both of which are chidren of the NetSim class.

Usage

```
## S3 method for class 'NetSim'
plot(
    x,
    y,
    ...,
    layout = "stress",
    title = "Network Simulation",
    node_color = "red",
    edge_color = "blue"
)
```

Arguments

х	a NetSim graph
У	ignored.
	ignored.
layout	a layout to display the graph. Layout must be a valid string. from the ggraph package. Default is "stress".
title	an optional title.
node_color	a color for the nodes. Default is blue.
edge_color	a color for the edges. Default is red.

Details

This method returns a ggraph object, which can be further refined using standard ggraph and ggplot facilities.

Value

A plot of classes 'ggraph' 'gg' and 'ggplot'

Author(s)

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Examples

6

plot.PointSim

Description

Plots the results of points simulated in a PointProcess or HaltonSeq class, which obht inherit methods from the PointSim class.

Usage

```
## S3 method for class 'PointSim'
plot(x, y, ..., title = "Simulated Points", color = "red")
```

Arguments

х	an object of class PointSim or one of its child classes
У	ignored
	ignored
title	an optional title. Default is "Simulated Points".
color	an optional color for the simulated points. Default is red.

Details

The returned plot can be refined with standard ggplot2 functions

Value

A plot of classes 'gg' and 'ggplot'

Author(s)

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Examples

```
# Load spacejamr object
data("RI")
ri_points <- PointSim(points = 10, window = RI, seed = 42)
plot(ri_points)</pre>
```

plot.spacejamr

Description

Plot method for the spacejamr class

Usage

```
## S3 method for class 'spacejamr'
plot(x, y, ..., title = "Spatial Window", fill = "blue")
```

Arguments

х	an object of class spacejamr.
У	ignored.
	ignored.
title	an optional title for the plot. Default is "Spatial Window".
fill	an optional fill for the plot. Default is blue.

Details

The returned plot can be refined with standard ggplot2 functions

Value

A plot of classes 'gg' and 'ggplot'

Author(s)

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Examples

```
# Load spacejamr object
data("RI")
```

plot(RI)

PointSim

Description

Creates a new Poisson Point Process in a spacejamr object

Usage

PointSim(points, window, type, seed)

Arguments

points	the number of points to simulate
window	a spacejamr object to use as the spatial extent
type	the type of simulation. poisson_process simulates a spatial Poisson process. halton simulates a Halton sequence where the maximal number of simulated points is the first argument.
seed	an optional seed

Value

An object of class PointSim that contains a geographical window of class 'owin'. Within this window are four objects. n: the number of simulated points. x: the x coordinates of the simulated points. y: the y coordinates of the simulated points. markformat: an empty place holder.

Author(s)

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Examples

```
# Load spacejamr object
data("RI")
# Poisson process
ri_points <- PointSim(points = 10, window = RI, seed = 42)</pre>
```

print.NetSim

Description

Plots a NetSim object and returns a ggraph object

Usage

S3 method for class 'NetSim'
print(x, ...)

Arguments

х	a NetSim object	
	ignored.	

Value

No return value, called for side effects

Author(s)

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Examples

print.PointSim Print information from a PointSim class

Description

Print method for both the PointProcess and HaltonSeq classes, which inherit methods from the PointSim class.

print.spacejamr

Usage

```
## S3 method for class 'PointSim'
print(x, ...)
```

Arguments

х	a PointSim object or a child object
	ignored.

Value

No return value, called for side effects

Author(s)

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Examples

```
# Load spacejamr object
data("RI")
```

ri_points <- PointSim(points = 10, window = RI, seed = 42)
print(ri_points)</pre>

print.spacejamr Print	information fro	om a spacejamr instance
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Description

Print method for the spacejamr class

Usage

```
## S3 method for class 'spacejamr'
print(x, ...)
```

Arguments

Х	a spacejamr object
	ignored.

Details

Provides a wrapper for the print.owin method in the spatstats.geom package.

Value

No return value, called for side effects

Author(s)

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Examples

Load spacejamr object
data("RI")

print(RI)

Geographical boundary of Rhode Island.

Description

A dataset containing Rhode Island's border and the coordinate reference system in which it is projected.

Usage

RI

Format

A spacejamr object with an owin window object and an integer denoting the projected coordinate reference system:

window geographical boundary of Rhode Island

crs the EPSG code for the coordinate reference system of the window ...

Source

https://www.rigis.org/datasets/edc::state-boundary-1989/about

spacejamr

Description

The spacejamr package provides three main types of functions: spacejamr, PointSim, and NetSim. They create new objects used in subsequent steps of network simulation, simulate spatial point processes, and create network objects. There are also plot, print, and summary methods for all objects and a compare_networks function to quickly compare two simulated networks.

Functions

APLNetwork compare_networks HaltonSeq RI plot.NetSim plot.PointSim plot.spacejamr PointProcess PowerLawNetwork print.NetSim print.PointSim print.spacejamr spacejamr summary.NetSim summary.spacejamr summary.PointSim

Author(s)

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summary.NetSim Summary of NetSim graphs

Description

Prints a summary of a NetSim object

Usage

S3 method for class 'NetSim'
summary(object, ...)

Arguments

object	a NetSim object
	ignored.

Value

No return value, called for side effects

Author(s)

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Examples

summary.PointSim Display summary information from a PointSim instance

Description

Prints a summary of information from either a PointProcess or HaltonSeq object, which are both child classes of the PointSim class.

Usage

```
## S3 method for class 'PointSim'
summary(object, ...)
```

Arguments

object	a PointSim object
	ignored

Value

No return value, called for side effects

summary.spacejamr

Author(s)

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Examples

```
# Load spacejamr object
data("RI")
```

```
ri_points <- PointSim(points = 10, window = RI, seed = 42)
summary(ri_points)</pre>
```

summary.spacejamr Print summary information of a spacejamr instance

Description

Summary method for the spacejamr class

Usage

```
## S3 method for class 'spacejamr'
summary(object, ...)
```

Arguments

object	a spacejamr object
	ignored.

Details

Provides a wrapper for the summary.owin method in the spatstats.geom package.

Value

No return value, called for side effects

Author(s)

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Examples

```
# Load spacejamr object
data("RI")
```

summary(RI)

Index

 $\texttt{compare_networks, 3}$

NetSim, 4

plot.NetSim, 5
plot.PointSim, 7
plot.spacejamr, 8
PointSim, 9
print.NetSim, 10
print.PointSim, 10
print.spacejamr, 11

RI, 12

spacejamr, 13
summary.NetSim, 13
summary.PointSim, 14
summary.spacejamr, 15