

# Package ‘processpredictR’

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**Type** Package

**Title** Process Prediction

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**Description** Means to predict process flow, such as process outcome, next activity, next time, remaining time, and remaining trace. Off-the-shelf predictive models based on the concept of Transformers are provided, as well as multiple ways to customize the models. This package is partly based on work described in Zaharah A. Bukhsh, Aaqib Saeed, & Remco M. Dijkman. (2021). ``ProcessTransformer: Predictive Business Process Monitoring with Transformer Network" <[arXiv:2104.00721](https://arxiv.org/abs/2104.00721)>.

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**VignetteBuilder** knitr

**NeedsCompilation** no

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confusion_matrix	<i>Confusion matrix for predictions</i>
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### Description

Confusion matrix for predictions

### Usage

```
confusion_matrix(predictions, ...)
```

### Arguments

<b>predictions</b>	<b>ppred_predictions</b> : A <code>data.frame</code> with predicted values returned by <code>predict.ppred_model()</code> .
...	additional arguments.

### Value

A `table` object that can be used for plotting a confusion matrix using `plot()`.

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create_model	<i>Define transformer model</i>
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## Description

Defines the model using the keras functional API. The following 4 process monitoring tasks are defined:

- outcome
- next\_activity
- next\_time
- remaining\_time
- remaining\_trace
- remaining\_trace\_s2s

## Usage

```
create_model(  
  x_train,  
  custom = FALSE,  
  num_heads = 4,  
  output_dim_emb = 36,  
  dim_ff = 64,  
  ...  
)
```

## Arguments

x_train	<code>data.frame</code> : A processed <code>data.frame</code> from <code>prepare_examples()</code> .
custom	<code>logical</code> (default <code>FALSE</code> ): If <code>TRUE</code> , returns a custom model.
num_heads	A number of attention heads of the <code>keras::layer_embedding()</code> .
output_dim_emb	Dimension of the dense embedding of the <code>keras::layer_embedding()</code> .
dim_ff	Dimensionality of the output space of the feedforward network part of the model ( <code>units</code> argument of the <code>keras::layer_dense()</code> ).
...	you can pass additional arguments to <code>keras::keras_model()</code> (ex.: name argument).

## Value

An object of class `ppred_model` and `list` containing a Transformer model (returned by `keras::keras_model()`) and some additional useful metrics.

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`create_vocabulary`      *Create a vocabulary*

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## Description

Creates a vocabulary of activities and outcome labels.

## Usage

```
create_vocabulary(processed_df)
```

## Arguments

`processed_df`      A preprocessed object of type `ppred_examples_df` returned by `prepare_examples()`.

## Value

A `list` consisting of:

- "keys\_x": `list` of activity labels
- "keys\_y": `list` of outcome labels (none for tasks "next\_time" and "remaining\_time")

---

`get_vocabulary`      *Utils*

---

## Description

Utils

## Usage

```
get_vocabulary(examples)
```

## Arguments

`examples`      a preprocessed dataset returned by `prepare_examples_dt()`.

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max_case_length	<i>Calculate the maximum length of a case / number of activities in the longest trace in an event log</i>
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### Description

Calculate the maximum length of a case / number of activities in the longest trace in an event log

### Usage

```
max_case_length(processed_df)
```

### Arguments

processed\_df A processed dataset of class [ppred\\_examples\\_df](#) returned by `prepare_examples()`.

### Value

An integer number of the maximum case length (longest trace) in an event log.

### Examples

```
library(processpredictR)
library(eventdataR)

df <- prepare_examples(patients)
max_case_length(df)
```

---

num_outputs	<i>Calculate number of outputs (target variables)</i>
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### Description

Calculate number of outputs (target variables)

### Usage

```
num_outputs(processed_df)
```

### Arguments

processed\_df A processed dataset of class [ppred\\_examples\\_df](#).

### Value

an integer number of outputs for supplying as an argument to a Transformer model, i.e. number of unique labels for a specific process monitoring task.

## Examples

```
library(processpredictR)
library(eventdataR)
df <- prepare_examples(patients)
num_outputs(df)
```

**plot.ppred\_predictions**

*Plot Methods*

## Description

Visualize metric

## Usage

```
## S3 method for class 'ppred_predictions'
plot(x, ...)
```

## Arguments

<code>x</code>	Data to plot. An object of type <b>ppred_predictions</b> .
<code>...</code>	Additional variables

## Value

A ggplot object, which can be customized further, if deemed necessary.

**ppred\_examples\_df**      *ppred\_examples\_df object*

## Description

object of type **ppred\_examples\_df** is a transformed event log returned by `prepare_examples_dt()`.

**ppred\_model**      *ppred\_model object*

## Description

object of type **ppred\_model** is a list returned by `processpredictR::create_model()` containing a custom keras functional (transformer) model and some other useful metrics of an event log.

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<code>ppred_predictions</code>	<i>ppred_predictions object</i>
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### Description

object of type `ppred_predictions` is a data.frame with predicted values returned by `predict.ppred_model()`.

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<code>prepare_examples</code>	<i>Convert a dataset of type <code>log</code> into a preprocessed format.</i>
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### Description

an event log is converted into a tibble where each row contains a cumulative sequence of activities per case. This sequence will eventually be feeded to the Transformer model's token embedding layer.

### Usage

```
prepare_examples(
  log,
  task = c("outcome", "next_activity", "next_time", "remaining_time", "remaining_trace",
          "remaining_trace_s2s"),
  features = NULL,
  ...
)
```

### Arguments

<code>log</code>	<code>log</code> : Object of class <code>log</code> or derivatives ( <code>grouped_log</code> , <code>eventlog</code> , <code>activitylog</code> , etc.).
<code>task</code>	<code>character</code> : a process monitoring task for which to prepare an event log.
<code>features</code>	<code>character</code> (default <code>NULL</code> ): additional features. Appends attributes (if present) <code>numeric_features</code> and/or <code>categorical_features</code> to a preprocessed event log.
<code>...</code>	additional arguments.

### Value

a preprocessed dataset of class `ppred_examples_df`.

### Examples

```
library(processpredictR)
library(eventdataR)

prepare_examples(patients, "next_activity")
```

`print.ppred_model` *Print methods*

## Description

Print methods

## Usage

```
## S3 method for class 'ppred_model'
print(x, ...)
```

## Arguments

<code>x</code>	<code>ppred_model</code> : An object of class <code>ppred_model</code> .
<code>...</code>	Additional Arguments.

## Value

prints a Transformer model from a list returned by `create_model()`.

`processpredictR` *processpredictR*

## Description

Means to predict process flow, such as process outcome, next activity, next time, remaining time, and remaining trace. Off-the-shelf predictive models based on the concept of Transformers are provided, as well as multiple ways to customize the models. This package is partly based on work described in Zaharah A. Bukhsh, Aaqib Saeed, & Remco M. Dijkman. (2021). "ProcessTransformer: Predictive Business Process Monitoring with Transformer Network" [arXiv:2104.00721](#).

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split_train_test	<i>Splits the preprocessed <code>data.frame</code>.</i>
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## Description

Returns train- and test dataframes as a list.

## Usage

```
split_train_test(processed_df, split = 0.7)
```

## Arguments

processed_df	A preprocessed object of type <code>ppred_examples_df</code> returned by <code>prepare_examples()</code> .
split	<code>numeric</code> (default 0.7): A train-test split ratio.

## Value

A `list` containing the train- and the test set objects.

## Examples

```
library(processpredictR)
library(eventdataR)

df <- prepare_examples(patients, "next_activity")
split_train_test(df, split = 0.8)
```

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stack_layers	<i>Stacks a keras layer on top of existing model</i>
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## Description

User friendly interface to add a keras layer on top of existing model.

## Usage

```
stack_layers(object, ...)
```

## Arguments

object	a <code>list</code> containing a model returned by <code>create_model()</code> .
...	functions for adding layers by using functional keras API. For example, <code>keras::layer_dense(units=32 activation="relu")</code> .

**Value**

a [list](#) containing an adapted Transformer model.

tokenize

*Tokenize features and target of a processed dataset of class [ppred\\_examples\\_df](#)*

**Description**

Tokenize features and target of a processed [ppred\\_examples\\_df](#) object to fit the Transformer model.

**Usage**

```
tokenize(processed_df)
```

**Arguments**

processed\_df A preprocessed object of type [ppred\\_examples\\_df](#) returned by `prepare_examples()`.

**Value**

A [list](#) of (sequence) tokens and additional numeric or categorical features.

vocab\_size

*Calculate the vocabulary size, i.e. the sum of number of activities, outcome labels and padding keys*

**Description**

Calculate the vocabulary size, i.e. the sum of number of activities, outcome labels and padding keys

**Usage**

```
vocab_size(processed_df)
```

**Arguments**

processed\_df A processed dataset of class [ppred\\_examples\\_df](#) from `prepare_examples()`.

**Value**

an integer number of vocabulary size to define the Transformer model.

**Examples**

```
library(processpredictR)
library(eventdataR)
df <- prepare_examples(patients)
vocab_size(df)
```

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